

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1	10/676155	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:52
S41	1	(calibrat\$3 with image with sensor) and ((geometric with travel with axis with bisector) same (total with (toe or toe-in) with angle) same (rear with axis) same vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:56
S42	1	(geometric with travel with axis with bisector) same (total with (toe or toe-in) with angle) same (rear with axis) same vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:57
S43	1	(calibrat\$3 with image with sensor) and (geometric with travel with axis with bisector) and (total with (toe or toe-in) with angle) and (rear with axis) and vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 18:59
S44	0	((alignment align\$3) with ((image with sensor) camera)) and (geometric with travel with axis) and (point\$3 with align\$3 with wheel) and vehicle and ((mak\$3 with point) same calibrat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:03
S45	0	((alignment align\$3) with ((image with sensor) camera)) and (geometric with travel with axis) and (point\$3 with align\$3 with wheel) and vehicle and ((mak\$3 with point) same calibrat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:04
S46	1	((alignment align\$3) with ((image with sensor) camera)) and (geometric with travel with axis) and (point\$3 with align\$3 with wheel) and vehicle and ((mark\$3 with point) same calibrat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:05
S47	0	((calibrat\$3 with datat) same (principal with point) same (principal with distance) same (distortion with parameter)) and (glass with pane) and (light with path)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/25 19:07

S48	1	((calibrat\$3 with data) same (principal with point) same (principal with distance) same (distortion with parameter)) and (glass with pane) and (light with path)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/26 14:26
S50	90	(calibrat\$3 with data) same ((principal with point) (principal with distance) (distortion with parameter) (glass with pane with light with path))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/26 14:28
S51	1	S50 and (geometric with travel with axis with vehicle)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/26 14:30
S52	1	S50 and (geometric with travel with axis) and vehicle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/26 14:30
S30	1	(intrinsic with calibration with data) and (camera with point) and (camera with distance) and (distortion with parameter) and (glass with pane)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2005/02/26 14:58